



Power System Analysis

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Background

This research project is focused on analyzing power systems under steady state operating conditions. This can be accomplished by solving the Power Flow problem. Power systems are composed of three subsystems: generation, transmission and distribution. The transmission and distribution networks consist of power transformers, transmission lines, capacitors, reactors and protection devices. The purpose of power system analysis is to determine the bus voltages and line power flows for a given set of bus load and scheduled power generation at the various power stations. The main challenge in solving the power flow problem is that the power flow equations are non-linear and thus require the use of an iterative method such as Newton Raphson for the solution.

$$P_k = \sum_{j=1}^N |V_k| |V_j| (G_{kj} \cos(\theta_k - \theta_j) + B_{kj} \sin(\theta_k - \theta_j))$$
$$Q_k = \sum_{j=1}^N |V_k| |V_j| (G_{kj} \sin(\theta_k - \theta_j) - B_{kj} \cos(\theta_k - \theta_j))$$



Methods

Creating a GUI: The first step of the research was to create graphical user interphase using Matlab.

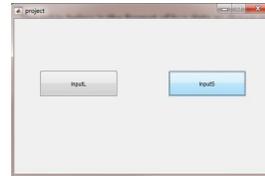


Fig1: First Sample GUI

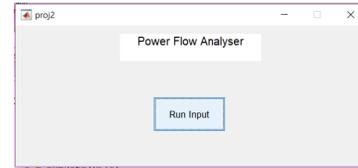


Fig2: Modified GUI

Writing Script files: After the GUI was created, the next step was to write Matlab scripts which run the Power Flow executable when the appropriate file is chosen on the GUI by the user. The Matlab script prompts the user to choose the file directory when a button is clicked

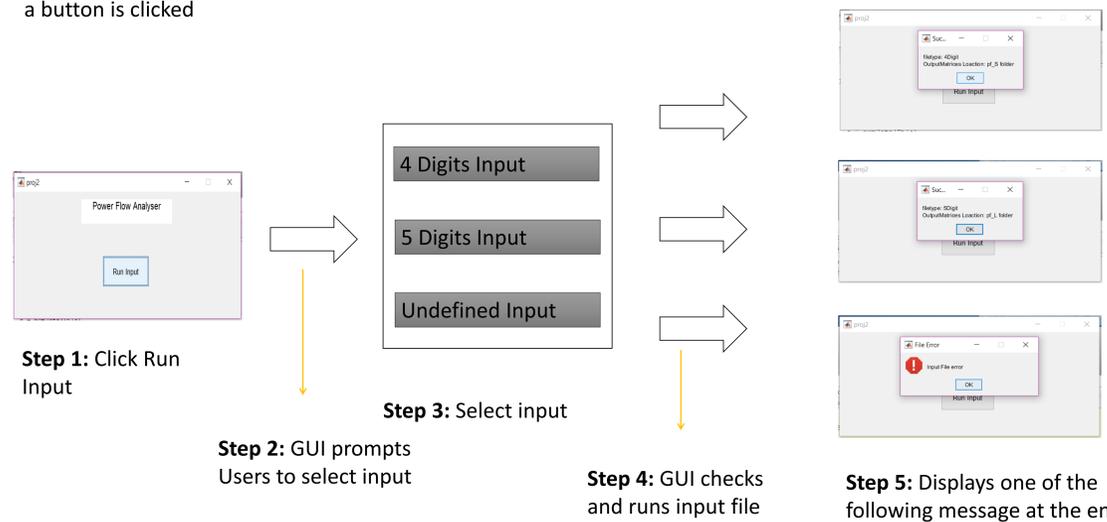


Figure 3: General Overview

Conclusions

- The main purpose of the research was to create a Graphical User Interphase(GUI) using Matlab and writing Matlab scripts to enable the GUI choose the right executable when a particular input file is selected in order to facilitate the utilization of power flow data files .
- During the course of the research, the above Graphical User Interphase was created where when its "Run Input" button is clicked, it enables the user to select an input file in a folder on the computer.
- When the user selects this file, the written Matlab scripts enable the GUI to check the input file format. The input files can be of two different formats (using 4 or 5 digit representation of bus numbers) but carry the same information.
- If the selected input file is in neither of these formats, an error message dialogue box is displayed and the program is terminated.
- The GUI was developed in a generic manner to read inputs files with different names. This was done by writing script files that copy and rename each appropriate input file prior to execution of the program.
- The Matlab scripts also create bus data matrix and branch data matrix after solving the power flow problem using the appropriate solver.
- When the GUI runs the input files successfully, a dialogue box is displayed at the end informing the user about the format of the input file and the location of the newly created output matrices

Introduction

Power systems are specified by two types of data: Bus Data (generation, load, voltages) and Branch Data (parameters R,X,B).Power system buses can be one of three different types. The **Slack Bus**, the **Generation Bus** (PV Bus) and the **Load Bus** (PQ Bus). The slack Bus is used as the reference bus where a reference angle(δ) and voltage(V) are specified.

Bus types	Quantities specified	Unknown values
Generator Bus	$ V , P_i$	Q_i, δ_i
Load Bus	P_i, Q_i	$ V , \delta_i$
Slack Bus	$ V , \delta_i$	P_i, Q_i

where;

P = Power
V = Voltage
Q = Reactive Power
 δ = Angle

Types of Buses

Results

After the GUI executes a particular type of input file using the appropriate executables, its saves the result in a common format. For this particular case the results are saved as Matlab files. This script also creates a bus data matrix and a branch data matrix from the output files as shown below.

BusNo	VoltageMagnitude	VoltageAngle	ActiveGeneration	ReactiveGeneration	ActiveLoad	ReactiveLoad
1	1.0600	0	232.2834	-16.8876	0	0
2	1.0450	-4.9800	40	42.3949	21.7000	12.7000
3	1.0100	-12.7200	0	23.3925	94.2000	19
4	1.0186	-10.3200	0	0	47.8000	-3.9000
5	1.0203	-8.7800	0	0	7.6000	1.6000
6	1.0700	-14.2200	0	12.2177	11.2000	7.5000
7	1.0620	-13.3700	0	0	0	0
8	1.0900	-13.3700	0	17.3568	0	0
9	1.0563	-14.9500	0	0	29.5000	16.6000
10	1.0513	-15.1000	0	0	9	5.8000
11	1.0571	-14.7900	0	0	3.5000	1.8000
12	1.0552	-15.0800	0	0	6.1000	1.6000
13	1.0505	-15.1600	0	0	13.5000	5.8000
14	1.0358	-16.0400	0	0	14.9000	5
15						

Figure 4: Bus Data Matrix Format

FromBus	ToBus	ActivePowerFlow	ReactivePowerFlow	
1	2	4	56.1388	-2.2868
2	3	73.1861	3.5653	
6	2	-152.5333	27.6541	
7	3	4	-23.3293	2.8089
8	3	2	-70.8660	1.5836
9	4	5	-61.2183	15.6651
10	4	9	16.0891	-0.3220
11	4	7	28.0858	-9.4216
12	4	2	-54.4617	3.3931
13	4	3	23.7005	-5.4212
14	5	6	44.0606	12.8237
15	5	1	-72.7882	2.5802
16	5	2	-40.6109	-1.6335
17	5	4	61.7348	-15.3662
18	6	11	7.3389	3.4650

Figure 6: Bus Data Matrix

FromBus	ToBus	ActivePowerFlow	ReactivePowerFlow	
4	2	4	56.1388	-2.2868
5	2	3	73.1861	3.5653
6	2	1	-152.5333	27.6541
7	3	4	-23.3293	2.8089
8	3	2	-70.8660	1.5836
9	4	5	-61.2183	15.6651
10	4	9	16.0891	-0.3220
11	4	7	28.0858	-9.4216
12	4	2	-54.4617	3.3931
13	4	3	23.7005	-5.4212
14	5	6	44.0606	12.8237
15	5	1	-72.7882	2.5802
16	5	2	-40.6109	-1.6335
17	5	4	61.7348	-15.3662
18	6	11	7.3389	3.4650

Figure 5: Branch Data Matrix Format

1	2	3	4	5
1	1.0600	0	232.2834	-16.8876
2	1.0450	-4.9800	40	42.3949
3	1.0100	-12.7200	0	23.3925
4	1.0186	-10.3200	0	0
5	1.0203	-8.7800	0	0
6	1.0700	-14.2200	0	12.2177
7	1.0620	-13.3700	0	0
8	1.0900	-13.3700	0	17.3568
9	1.0563	-14.9500	0	0
10	1.0513	-15.1000	0	0
11	1.0571	-14.7900	0	0
12	1.0552	-15.0800	0	0
13	1.0505	-15.1600	0	0
14	1.0358	-16.0400	0	0
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Figure 7: Branch Data Matrix

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