# **Calibration**

**Flowchart:**









Our results indicate that the same calibration approach can be utilized when the CMOS chip and FSL are available. The code and algorithm developed in this project can be modified to work directly with both, catering to the specific number of bits and delays. In the future, machine learning can be implemented into the algorithm to detect the specific signal frequency from the output voltage and the attenuation level to create specialized input-output equations that are not limited to 10 MHz.





# Northeastern University<br>College of Engineering

Northeastern University **Michael B. Silevitch and Claire J. Duggan Center for STEM Education** 

# Automatic Calibration for Improved Suppression of Interference Signals in Wireless Receivers

**Jacky Li, YSP Student,** *Boston Latin School*  **Emily Zhang, YSP Student,** *Sharon High School* Yunfan Gao, Electrical and Computer Engineering, *Northeastern University*  Thomas Gourousis, Electrical and Computer Engineering, *Northeastern University*  Minghan Liu, Electrical and Computer Engineering, *Northeastern University*  Prof. Marvin Onabajo, Electrical and Computer Engineering, *Northeastern University*

# Experimental Methods and Conclusion

### Abstract

# Acknowledgements

● Our code is able to successfully detect a change in the power of the incoming signal and then recalibrate the attenuation level to match our reference voltage

• To the right, we have an example of the power changing from 0 dBm to -10 dBm. We can see how the output voltage (blue dashed) automatically calibrates back to the reference voltage of 1.57 volts (orange)

With the increasing number of wireless devices in our surroundings, it becomes increasingly important to design radio frequency receivers for wireless communications with enhanced capabilities to suppress unwanted interference signals. The ongoing research efforts involve the development of new devices, circuits, and digital algorithms to improve the robustness of wireless receivers. As part of this goal, this research project focuses on the prototyping of an automatic calibration approach with an Arduino microcontroller, which is done dynamically on signal power detection and the use of digital control circuits. In the experiments, an attenuator is used to optimize the suppression of interference in analog radio frequency front-ends of wireless receivers.

# **Background**

John O'Malley, 2011. Schaum's Outline of Basic Circuit. Analysis Revised Second Edition. McGraw-Hill Education.

Razavi, B., 2021. Fundamentals of Microelectronics. John Wiley & Sons.

# References

**Analog & Mixed-Signal Integrated Circuit Research Laboratory** Marvin Onabajo, Professor Yunfan Gao, Ph. D. Candidate Minghan Liu, Ph. D. Candidate Thomas Gourousis, Ph. D. Candidate

**Center for STEM Education**

Claire Duggan, Executive Director Jennifer Love, Associate Director Theodore Lourie, Victoria Berry, Angelina Le, and Michael Marchev, YSP Coordinators

Nicolas Fuchs, Program Manager Mary Howley, Administrative Officer

## **Automatic Calibration Example:**

#### **Interference:**

Interference involves unwanted signals that disrupt desired signals in communication systems. Low-power receivers struggle with interference due to their narrow dynamic range, leading to issues like slow data transfer, dropped calls, buffering, and reduced battery life.

#### **Frequency Selective Limiter (FSL):**

The FSL is a more effective solution compared to traditional methods such as simple filtering. It attenuates signals within specific frequency ranges, especially those exceeding a predefined power threshold  $(P_{th})$ , helping to prevent distortion

in both the targeted and adjacent frequency bands.

#### **Automatic Calibration:**

Automatic calibration enhances the effectiveness of an FSL by allowing dynamic adjustment of attenuation levels to match varying signal environments. This ensures better interference reduction and adaptation to changes in signal strength.

#### **Component data collection:**

**Dynamic Adjustment and Testing:**

- Tested how to set the attenuation level
- Recorded max. input/output voltages to prevent overload
- Arduino Mega 2560 Rev3
	-
	-
	-

#### ● Using the Arduino, we dynamically adjusted the attenuator based on a feedback control algorithm in the IDE.







# **Results**

Constant 0 dBm Input --- Output  $2.0 -$ Reference — Minimum  $1.9 -$ Maximun  $\sum 1.8$  $\frac{2}{3}$  1.7  $1.5$  $1.4$  $^{1}$  1.3 1.1  $1.0 -$ 10 Time (ms) -10 dBm Jump From 0 dBm at  $\sim$ 19.5 Milliseconds  $2.1$ ncrease or decrease  $---$  Output  $2.0 \cdot$ Reference attenuation by an Minimum  $1.9$ increment of 0.5 dB Maximum  $\widehat{\ge}$  1.8  $\frac{6}{2}$  1.7  $= 1.6$ ------------------------------ត្ត 1.5 -Sets pins to correct  $\frac{1}{60}$  1.4 attenuation of lows ິ 1.3 and high  $1.2$  $1.1$  $1.0$ 12 16 18 20 10 14 Time (ms)

#### **Equipment/Software Used:**



![](_page_0_Picture_15.jpeg)

![](_page_0_Picture_16.jpeg)

- Power detector input-output
- characteristics were measured
- to find an equation for
- converting dBm to Volts
- Using the inverse, we convert from Volts to dBm in our code
- **Volt = -0.0239 \* dBm + 1.09**
- **dBm = -41.841 \* Volt + 45.6**